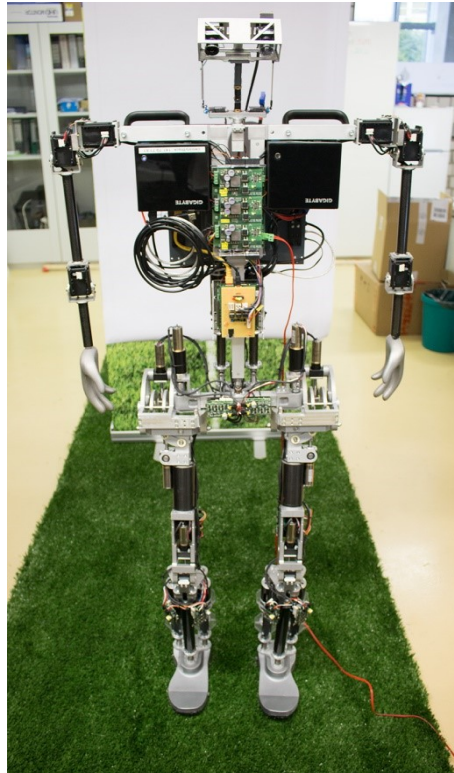


Sweaty



Robot Name:	Sweaty
Height of the robot:	160.5 cm
Weight of the robot:	20.6 kg
Walking speed:	0.2 m/s
Number of degrees of freedom:	23
Type of motors:	14 Maxon, 6 Robotis Dynamixel, 3 Volz
Type of sensors used:	2 UI-3241 LE-C 1280x1024 1:1.8
Computing units:	Gigabyte Brix I7 4Core 3.7 GHz (Decision, Motion) Gigabyte Brix I5, 2Core, GTX 760 GPU (Vision)
Height shoulder:	137 cm
Width shoulder:	49 cm
Height hip:	76 cm
Height torso:	38 cm
Length arm:	50 cm (actual, to be modified to 65 cm)
Number and Typ of Buses	TCP/IP, CAN, RS485
Battery:	2 LiPo 7S1P 4 Ah 40C